RAPID-AIR

OPERATING INSTRUCTIONS FOR
P1V, P1M, P4V, P4M, P1W, P1WM
RAPID-ROLL POWER ROLL

RAPID-AIR
4601 KISHWAUKEE ST.
ROCKFORD, IL. 61109-2925
PHONE: (815) 397-2578
FAX: (815) 398-3887
WEB SITE: www.rapidair.com
# TABLE OF CONTENTS

<table>
<thead>
<tr>
<th>PAGE</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1.</td>
<td>RAPID-ROLL &quot;HEAD ONLY&quot; DRAWING</td>
</tr>
<tr>
<td>2.</td>
<td>SET UP &amp; CAPACITIES</td>
</tr>
<tr>
<td>3.</td>
<td>KEYPAD FUNCTIONS</td>
</tr>
<tr>
<td>4.</td>
<td>KEYPAD FUNCTIONS</td>
</tr>
<tr>
<td>5.</td>
<td>KEYPAD FUNCTIONS</td>
</tr>
<tr>
<td>6.</td>
<td>JOG SPEED ADJUSTMENT &amp; DANCER ARM CALIBRATION</td>
</tr>
<tr>
<td>7.</td>
<td>JOG SPEED ADJUSTMENT &amp; DANCER ARM CALIBRATION</td>
</tr>
<tr>
<td>8.</td>
<td>MAINTENANCE</td>
</tr>
<tr>
<td>9.</td>
<td>TROUBLESHOOTING</td>
</tr>
<tr>
<td>10.</td>
<td>TROUBLESHOOTING</td>
</tr>
<tr>
<td>11.</td>
<td>CABINET ASSEMBLY DRAWING</td>
</tr>
<tr>
<td>12.</td>
<td>P1V ASSEMBLY DRAWING</td>
</tr>
<tr>
<td>13.</td>
<td>P1M ASSEMBLY DRAWING</td>
</tr>
<tr>
<td>14.</td>
<td>P4V ASSEMBLY DRAWING (sheet 1 of 2)</td>
</tr>
<tr>
<td>15.</td>
<td>P4V ASSEMBLY DRAWING (sheet 2 of 2)</td>
</tr>
<tr>
<td>16.</td>
<td>P4M ASSEMBLY DRAWING (sheet 1 of 2)</td>
</tr>
<tr>
<td>17.</td>
<td>P4M ASSEMBLY DRAWING (sheet 2 of 2)</td>
</tr>
<tr>
<td>18.</td>
<td>P1W ASSEMBLY DRAWING</td>
</tr>
<tr>
<td>19.</td>
<td>P1WM ASSEMBLY DRAWING</td>
</tr>
<tr>
<td>20.</td>
<td>WIRING DIAGRAM</td>
</tr>
</tbody>
</table>
ROLL PRESSURE ADJUSTING KNOB

DANCER ARM

PUSHBUTTON CONTROL ASSEMBLY

ROLL PRESSURE ADJUSTING KNOB

STOCK

ECCENTRIC ADJUSTMENT

MOTOR

ENTRANCE GUIDES
1. Your Rapid-Roll Power Roll is fully assembled and ready to be put into position. Visually inspect unit for damaged or loose parts due to shipment. If there is physical damage contact carrier.

2. Install your Rapid-Roll Power Roll on a level surface with sufficient clearance for loading material and adjusting pinch roll pressure. Align and center your unit to the device that will be supplying the stock. For safe operation, bolt unit to floor. Before bolting your unit to the floor, check for the longest feed length and position your Rapid-Roll so that there will be about two or three feed lengths in the storage loop without re-inducing coil set in the material.

3. To set up unit, place short length of stock (approx. 4 ft. long) on the bottom pinch roll making sure the top pinch roll is raised. Set entrance guide rolls to maintain stock position. Apply light pinch roll force (using pinch roll adjusting knob) to the stock to insure adequate assisting pulling force on the stock while operating. Never overload the pinch rolls, this could damage the stock by extrusion causing permanent deformation.

### SET UP & CAPACITIES

<table>
<thead>
<tr>
<th>MODEL</th>
<th>MAX. MATERIAL WIDTH</th>
<th>Recommended Operating Range</th>
<th>Speed</th>
<th>Max. Speed in./min.</th>
<th>AC Input Power Required</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1V</td>
<td>1.50&quot; (38mm)</td>
<td>.0005-.075&quot; (.0127-.191mm)</td>
<td>Standard</td>
<td>0-700&quot; (1778cm)</td>
<td>1/4hp, 115vac, 1ph</td>
</tr>
<tr>
<td>P1M</td>
<td>1.50&quot; (38mm)</td>
<td>.0005-.075&quot; (.0127-.191mm)</td>
<td>Medium</td>
<td>0-1400&quot; (3556cm)</td>
<td>1/2hp, 115vac, 1ph</td>
</tr>
<tr>
<td>P4V</td>
<td>4.00&quot; (102mm)</td>
<td>.0005-.060&quot; (.0127-.152mm)</td>
<td>Standard</td>
<td>0-700&quot; (1778cm)</td>
<td>1/4hp, 115vac, 1ph</td>
</tr>
<tr>
<td>P4W</td>
<td>4.00&quot; (102mm)</td>
<td>.0005-.060&quot; (.0127-.152mm)</td>
<td>Medium</td>
<td>0-1400&quot; (3556cm)</td>
<td>1/4hp, 115vac, 1ph</td>
</tr>
<tr>
<td>P1W</td>
<td>wire</td>
<td>.005-.150&quot; (.127-3.81mm)</td>
<td>Standard</td>
<td>0-700&quot; (1778cm)</td>
<td>1/4hp, 115vac, 1ph</td>
</tr>
<tr>
<td>P1WM</td>
<td>wire</td>
<td>.005-.150&quot; (.127-3.81mm)</td>
<td>Medium</td>
<td>0-1400&quot; (3556cm)</td>
<td>1/2hp, 115vac, 1ph</td>
</tr>
</tbody>
</table>

CAUTION - Disconnect electrical power before performing any service to this machine.
Prior to applying power to your Rapid-Roll Power Roll the operator should review all controls on this machine. See pages 4-5 in this manual for a summary of these controls.

**KEYPAD FUNCTIONS**

In Stop Mode: Select Loop Arm or External Loop Control. Position Loop Sensor Above Material Loop. Set Estimated % Max Speed, Loop Height and Loop Range.

In Run Mode: Adjust % Max Speed, Loop Height and Loop Range for Smooth Operation.

**POWER ROLL KEYPAD**

**REMOTE INTERFACE PORT "D"**
KEYPAD FUNCTIONS

On/Off switch
This illuminated switch is the main power switch for the controller. It must be "ON" for the Rapid-Roll to function.

Reset switch
This is the main circuit breaker for the Rapid-Roll.

Run/Stop/Jog
In the Run mode, if the dancer arm is moved the pinch rolls will turn.
In the Jog mode, the jog button has to be depressed for the pinch rolls to turn. Jog function is used mainly for setup.
In the Stop mode there is no movement of the pinch rolls.

Loop arm/external switch
When using a dancer arm, select loop arm button to display "LV" for vertical. This button will also allow you to select "LH" for horizontal. ("LH" is used for Pallet Master decoilers only)
When using an external loop control, select external loop to display "RT" for RTB or "RS" for RS2.

Note: Remote interface port "D" connector, if used, communicates with external loop control.

Warning! - Never plug any type of computer or non Rapid-Air equipment into this plug or severe damage will result. Consult factory when installing new external controls.
KEYPAD FUNCTIONS

Loop range/height

The loop range function selects the degree of arm movement to achieve maximum motor speed. If a loop range of "0" was selected the arm would only have to travel approximately 6° to have the Rapid-Roll at full speed. If a loop range of "8" was selected the arm would travel approximately 60° to have the Rapid-Roll at full speed. This function is active in the "RUN" mode.

The loop height function selects the degree of arm movement to start pinch roll rotation. If a loop range of "0" was selected the arm would only have to travel approximately 6° to start pinch roll rotation. If a loop range of "8" was selected the arm would travel approximately 60° before starting pinch roll rotation.

To set the loop height, thread up the material with the dancer arm resting on the material. If the Rapid-Roll is running with the dancer arm in this position adjust the loop height until Rapid-Roll stops. This is your new at rest position. This function is active in the "RUN" mode.

% Speed setting

The % speed setting allows you to adjust the maximum speed the pinch rolls will rotate. This should be set to maintain a constant feed rate. This function is active in the "RUN" mode.
JOG SPEED ADJUSTMENT & DANCER ARM CALIBRATION

Your Rapid-Roll was shipped with the dancer arm set up for its correct position so the only thing that has to be reset would be the jog speed if you need your unit to jog faster or slower.

To reset the jog speed, turn off the main power switch. Press and hold the "Run/Stop/Jog" button while turning the main power switch on. The first screen you will see will display the jog speed percentage.

| JOG SPEED 23% + | % SPEED + |
|________|________|
| NEXT - | SPEED - |

To increase the jog speed, press the "Start Speed" pushbutton. If you want to decrease the jog speed press the "Start Speed" pushbutton.

The jog speed is shown in the percent of maximum jog speed. Once you have set the desired jog speed push the "Run/Stop/Jog" button once for next. Your jog speed is now set.

The next screen asks if you want to set up the sensor (commonly referred to as "dancer arm calibration"). Use the percent speed buttons to select "yes" or "no".

Select "no" if all you wanted to do was change the jog speed, select "yes" if you want to calibrate the dancer arm by resetting the sensor.

| SETUP SENSOR YES | AFTER MAKING YOUR SELECTION, PRESS "RUN/STOP/JOG" FOR NEXT. |
|________|________|
| NEXT NO | |

If you selected "yes" the next screen asks you to set the low set point. If the dancer arm is resting on the positive stop then just save this setting by pushing the "Run/Stop/Jog" button.

| SENSOR LOW SETPOINT SAVE | xxx |
|________________________|______|
JOG SPEED ADJUSTMENT & DANCER ARM CALIBRATION

The next screen is for setting the high set point. Raise the dancer arm to it's upper stop position and press the "Run/Stop/Jog" button once to save this setting.

SENSOR HIGH SETPOINT
SAVE XXX

The next screen is to set the offset of the program. Potentiometers are hard to get set perfectly so we've built in an offset. After setting the high & low points, with the dancer arm resting on the positive stop, put the unit in the "Run" mode. If the unit starts running with the dancer arm on the positive stop then an offset needs to be put in. If an offset needs to be put in go through the setup procedure again until you get to the low offset screen. Using the percent speed buttons put in an offset value of -3 to -5. Press the "Run/Stop/Jog" button to save this setting.

LOW OFFSET +0 +
NEXT -

You now have set the dancer arm limits. The next screen to appear allows you to exit the setup. Use the percent speed button to enter "yes or no".

EXIT SETUP YES NO

If "yes" was selected press "Run/Stop/Jog" button and the next screen appears.

SHUT OFF POWER TO SAVE AND EXIT

Power off unit, the dancer arm is now ready for production running.
**MAINTENANCE**

Gearbox lubrication - change oil every 1000 hours as follows:

Electrical - all brushes on motors should be checked every 1500-2000 hours.

Your Rapid-Roll Power Roll was shipped from the factory with the upper & lower pinch rolls parallel to each other. If these pinch rolls should happen to get out of parallel, use eccentric shaft to adjust rolls. See diagram page 1 for location of eccentric shaft. Loosen socket head cap screw in center of shaft. Turn shaft until rolls are parallel with each other. You should be able to grip .001 thick shim stock along entire width of rollers. After adjustment is made, re-tighten socket head cap screw.
TROUBLESHOOTING

MAIN SWITCH ON BUT NOT LIT
1. Circuit breaker tripped
   a. Reset circuit breaker
2. Unit not plugged into main power
   a. Plug into main power
3. No power in incoming line
   a. Check outlet
   b. Check power cord
4. Loose wiring
   a. Check terminals and connections

MOTOR CREEPS IN STOP POSITION
1. "Min." speed pot on RAMM board out of adjustment
2. Offset in dancer arm setup out of adjustment (see page 8)

UNIT ON BUT MOTOR WON'T RUN
   (armature voltage present on RAMM board)
1. Check motor wiring
   a. replace motor cord or correct motor wiring (consult factory)
2. Check motor
   a. Worn brushes or defective motor (consult factory)
   b. Check for oil in motor, gear box oil seal may have failed

UNIT ON BUT MOTOR WON'T RUN
   (no armature voltage present on RAMM board)
1. Selector switch not in "RUN" position
   a. Turn selector switch to "RUN" position
2. If running with a dancer arm control
   a. Check that the external/loop arm function is in the loop arm position
3. If running with external control
   a. Check that the external/loop arm function is in the external position
4. Loop height switch setting to high
   a. Set height setting to "0"
TROUBLESHOOTING

5. Percent speed function set too low  
   a. Adjust percent speed function to 100%

6. Fuses blown  
   a. Check fuses & circuit breaker

7. No AC voltage at DC drive board  
   a. Check wiring

8. Check signal voltage between P2 to P1 on DC drive  
   0-6 VDC - RAMM  
   0-9 VDC - Regen drive  
   while moving dancer arm  
   a. If there is a signal, check continuity between I1 & I2  
      If no continuity, replace DC drive or consult factory

9. Check pico fuse on 69100804 board (F1)  
   a. Replace fuse, 1 amp pico fuse-consult factory

![Diagram of 69100804 Board, 29100021 Potentiometer, 69100014 Board]
P4V ASSEMBLY DRAWING
(SHEET 2 OF 2)