



STRAIGHTENER OPERATING INSTRUCTIONS

MODELS

SC SERIES

**(ADJUSTABLE PLATEN STOCK STRAIGHTENER –
INCLUDES SA3 THROUGH SCH18)**

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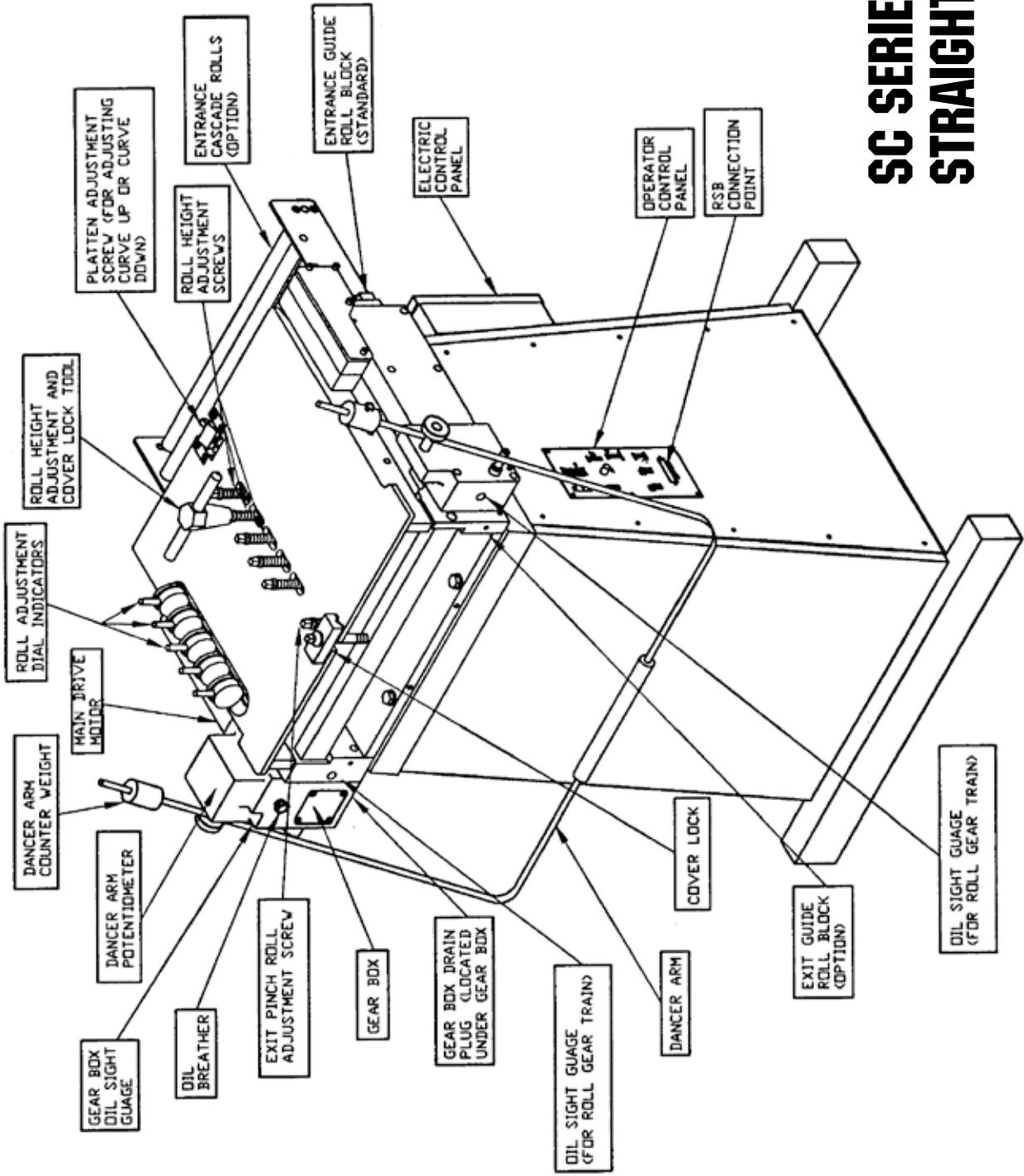
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SC SERIES STRAIGHTENERS



SPECIFICATIONS FOR STOCK STRAIGHTENERS

	MODEL	PULL CAP. FROM NON-POWERED REEL	MAX STOCK WIDTH	EFFECTIVE STRAIGHTEN RANGE	--ROLL DIAMETER--		SPEED RANGE IN/MIN	MOTOR SIZE	POWER REQUIREMENTS		
					STRAIGHTEN IN.	PINCH IN.			VOLTAGE	PHASE	
STANDARD SPEED	SA3		3	.005-.015	3/8	1-1/2	0-700	1/4	115	1	
	SB4	500 LB.	4	.007-.030	5/8	1-1/2	0-700	1/2	115	1	
	SB6	500 LB.	6	.007-.025	5/8	1-1/2	0-700	1/2	115	1	
	SC6	1500 LB.	6	.015-.085	1-1/4	1-1/4	0-825	1	115	1	
	SC12	1500 LB.	12	.015-.050	1-1/4	1-1/4	0-825	1	115	1	
	SC18	1500 LB.	18	.015-.036	1-1/4	1-1/4	0-825	1	115	1	
MEDIUM SPEED	SAM3		3	.005-.015	3/8	1-1/4	0-1400	1/2	115	1	
	SBM4	500 LB.	4	.007-.025	5/8	1-1/4	0-1400	1/2	115	1	
	SBM6	500 LB.	6	.007-.025	5/8	1-1/4	0-1400	1/2	115	1	
	SCM6	1500 LB.	6	.015-.070	1-1/4	1-1/4	0-1650	2	240	1	
	SCM12	1500 LB.	12	.015-.050	1-1/4	1-1/4	0-1650	2	240	1	
	SCM18	1500 LB.	18	.015-.036	1-1/4	1-1/4	0-1650	2	240	1	
HIGH SPEED	SCH6	1500 LB.	6	.015-.075	1-1/4	1-1/4	0-4125	3	240	1	
	SCH12	1500 LB.	12	.015-.050	1-1/4	1-1/4	0-4125	3	240	1	
	SCH18	1500 LB.	18	.015-.036	1-1/4	1-1/4	0-4125	3	240	1	

****ALL STRAIGHTENERS HAVE 11 ROLLS, 5 UPPER & 6 LOWER ROLLS**
*****ALL SC STRAIGHTENERS HAVE THE OPTION OF DIAL INDICATOR ROLL POSITION GAUGES**

INSTALLATION

Operating Instructions for SC Series Powered Straightener

The straightener that you just received is fully assembled and tested and ready to be put into position.

CAUTION: Due to shipment vibration, it should be checked to be sure that all screws and bolts are secure and all electrical components are in place inside the cabinet, visually inspect the complete machine for physical damage due to shipment and handling. If the straightener was damaged in shipment, contact the carrier first and then Rapid-Air.

Install the straightener on a level surface with sufficient clearance for loading the material and adjusting the roller pressure for straightening. Align and center the straightener to the

device that it will be supplying the straightened stock. The straightener should then be bolted to the floor especially when used to pull stock from a non-powered reel.

CAUTION: Before bolting the straightener down, check for the longest feed length to be run. The straightener should be set so that there will be about two or three feed lengths in storage in the loop without re-inducing coil set in the material.

The standard speed straightener is completely self contained and only needs to be plugged into a 20 amp, 120 VAC, 60 HZ outlet. If an extension cord is used as a source to the straightener power, it should be a

minimum 12 gauge wire to keep the voltage losses down and also for electrical safety reasons. **Please check your local safety codes.**

The medium and high speed straighteners require 230 VAC, 60 HZ, 1PH as the supply voltage. Please refer to the schematics in the manual for required fuse sizes. **Please check your local safety codes.**

Turn on the main power button and run a test cycle checking the jog (using the jog button) and run (using the dancer arm to test that the speed varies if using the proportional control). Test all electrical features before continuing.

START UP PROCEDURE

Prior to applying power to the straightener, all the controls on the machine should be reviewed. A brief summary is listed below.

Main Console And Controller

The main control console with controls is mounted on the cabinet of the straightener. Located on the face of the console are five switches, one potentiometer, one push-button and one or two circuit breaker reset switches, which are explained below.

1. ON/OFF SWITCH

This illuminated switch is the main power switch for the controller. On the 120 VAC straighteners, it will be a toggle switch and on the 230 VAC version it will be a mushroom push-button. It must be "ON" for the straightener to function.

2. RESET BUTTONS (circuit breaker)

120 VAC.

a. 15 amp – This is the main circuit breaker for the straightener.

b. 3 amp – This is the main circuit breaker for the "D-SUB" (25 pin) connector. Any shorting or overloads would trip this breaker.

240 VAC.

a. 3 amp – This is the main circuit breaker for the "D-SUB" connector. Any shorting or overloads would trip this breaker.

3. RUN/STOP/JOG SELECTOR SWITCH

a. If "RUN" was selected and the dancer control arm was raised, the straightener rolls would rotate. If "STOP" was selected then none of the functions would work. If "JOG" was selected then the jog button has to be depressed to have the straightener rolls rotate.

4. JOG BUTTON

Used for intermittent movement of the straightener rolls and mainly for setup. The jog speed can be adjusted by rotating the R3 potentiometer on the 69100079 board in the control sub panel.

5. % SPEED POTENTIOMETER

The % speed potentiometer adjusts the maximum speed that the straightener rolls can rotate regardless of the dancer arm height. It should be set to maintain a constant material feed rate through the straightener.

6. DANCER ARM LOOP HEIGHT AND RANGE ADJUSTMENT

a. Loop Range – The loop range switch adjusts the amount of travel that the dancer arm will move to provide the full range of speed on the straightener. It has three positions with a "0" as the least travel from slowest to fastest speed and a "2" has the most movement between slowest to fastest speed.

b. Loop Height – The loop height switch is used for setting the start position of the control arm. It has three positions with the "0" setting having the start position at the dancer arm rest position and the "2" having the start position somewhat higher than the dancer arm rest position. This setting will determine the dancer arm angle that the reel will start turning. This function is used to accommodate different thickness of material which would

have a different bend radius thus requiring the dancer arm to be at a height somewhat above the home position when at rest.

7. LOOP ARM / EXTERNAL SWITCH

This switch is used to select whether the material loop is controlled by the dancer arm or an external loop control. If LOOP ARM is selected then the control will monitor the dancer arm movement. If EXTERNAL is selected then the control will monitor whatever is plugged into the "D-SUB" (25 pin) connector.

8. REMOTE INTERFACE PORT "D" CONNECTOR

This 25 pin connector, located on the lower portion of the console is used to communicate with external loop equipment. The RSB, RTB, & RTA will plug into the port and can immediately be implemented.

CAUTION: Never plug any type of computer or non Rapid-Air equipment into this plug or severe damage could result. Always consult the factory when installing different external controls for advice on compatibility and wiring information.

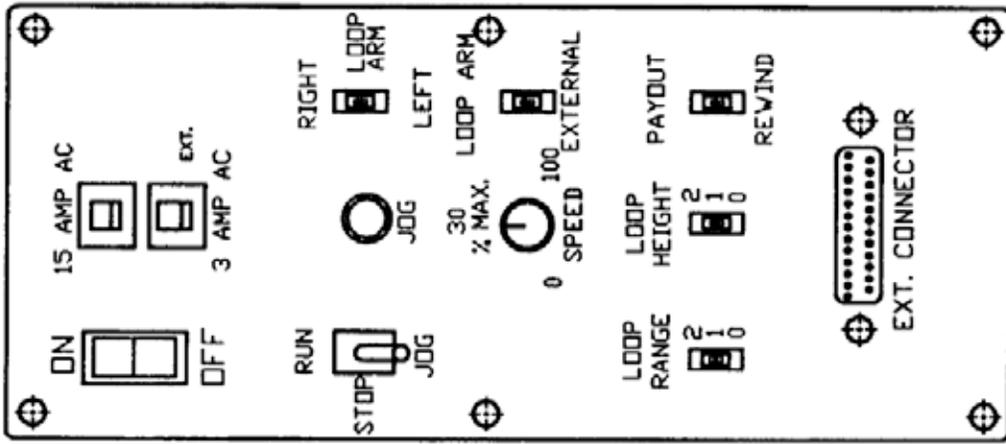
9. PANEL MOUNTED ELECTRICAL COMPONENT DESCRIPTION

69100034 board – proportional control board

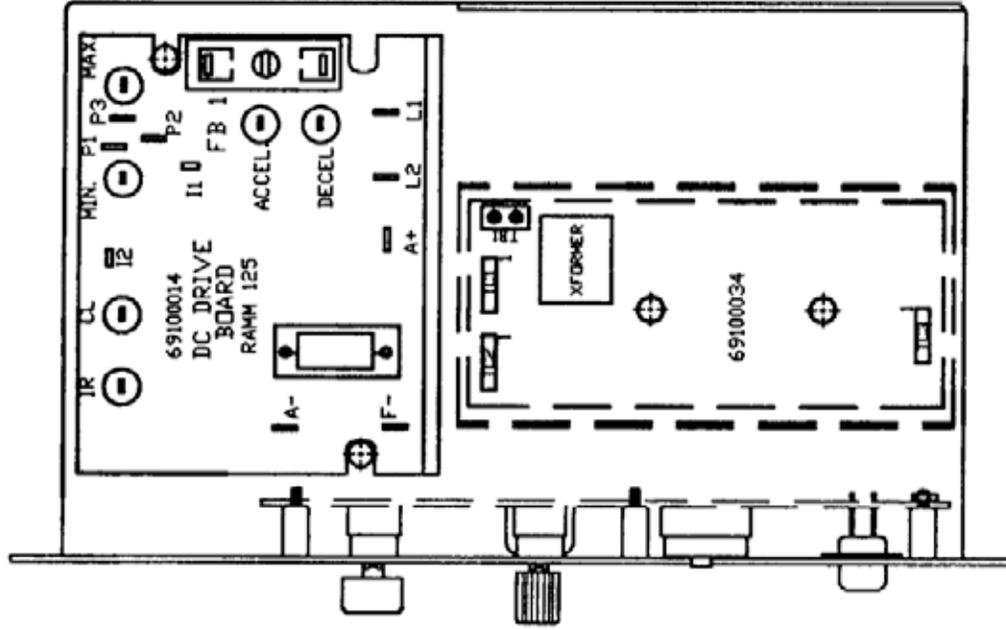
69100076 board – component interface board

69100014 board – (RAMM) D.C. motor control board [120 VAC, 1 PH]

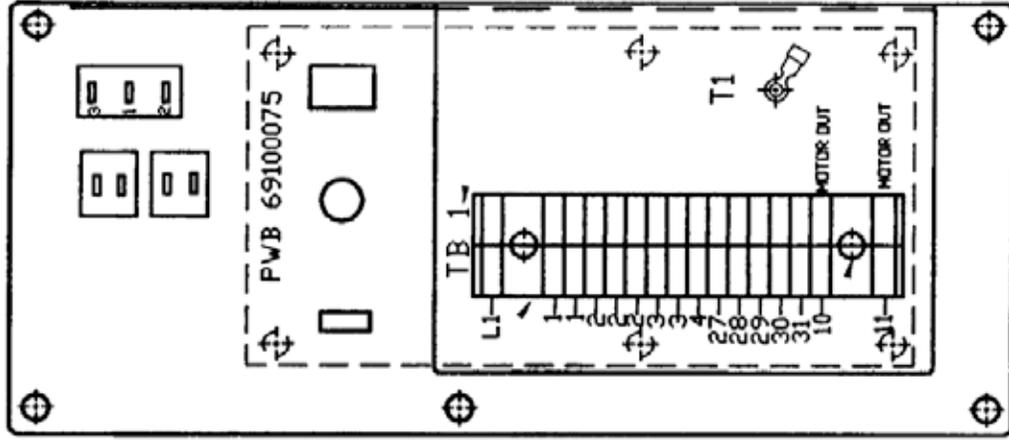
69100038 board – (RAMM) D.C. motor control board [240 VAC, 1 PH]



FRONT VIEW

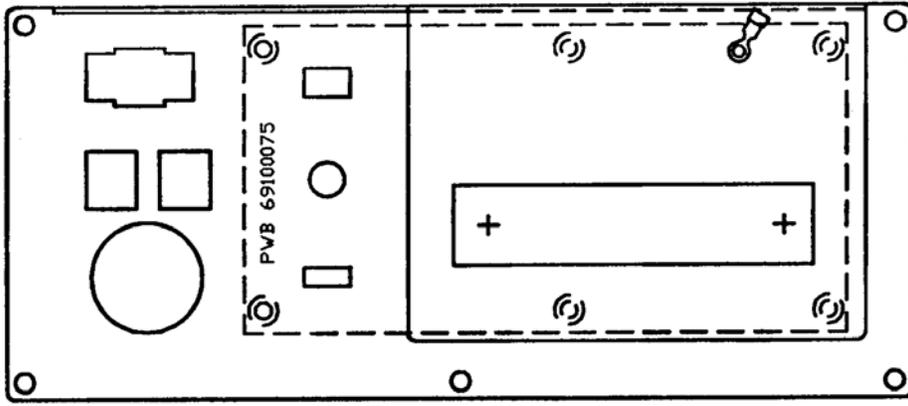
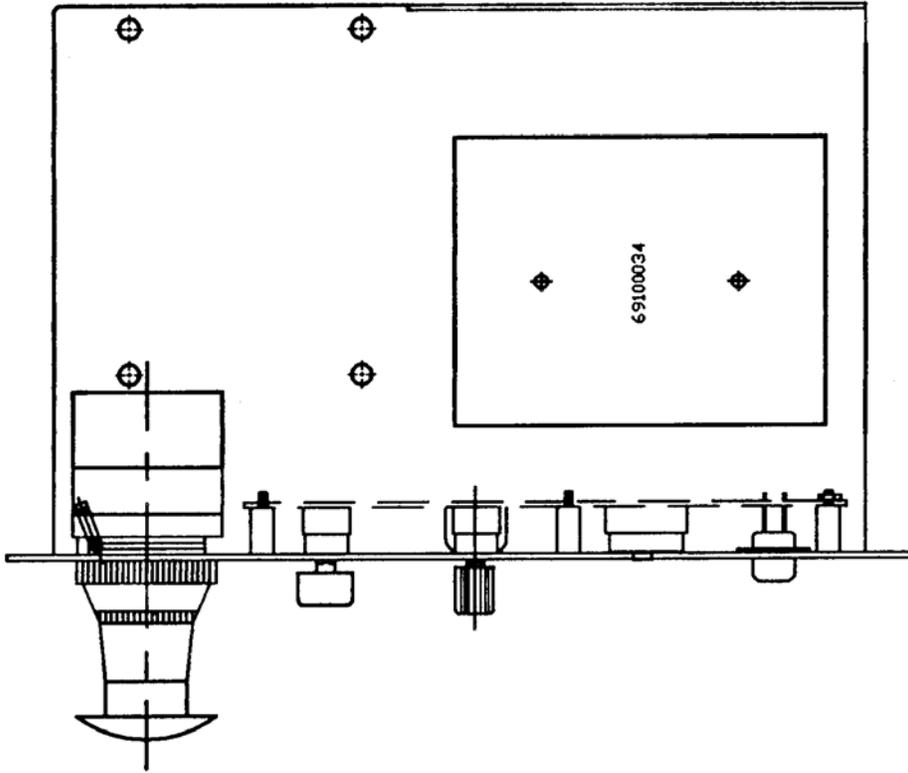
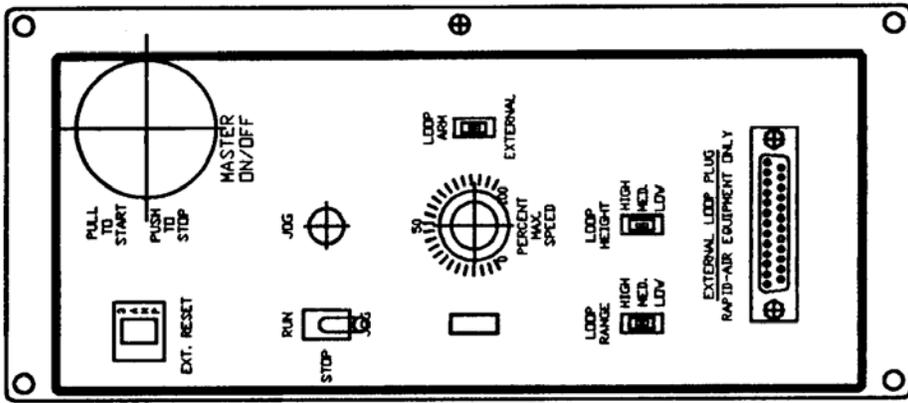


SIDE VIEW



BACK VIEW

1 HP AND LOWER CONTROL

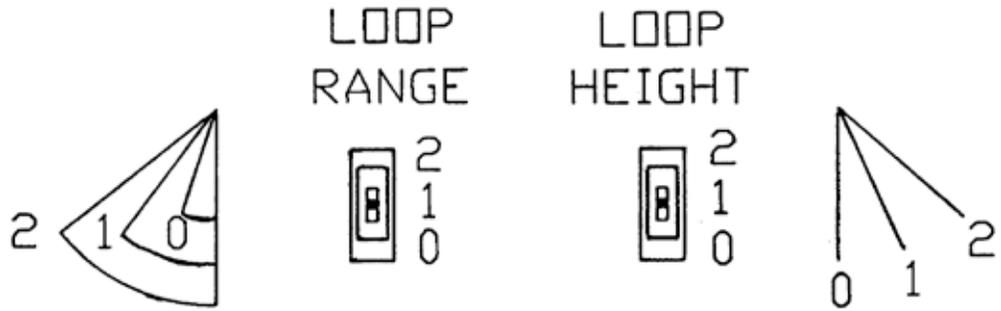


2 & 3 HP CONTROL

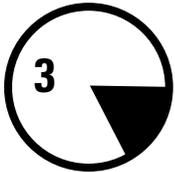
DANCER ARM LOOP

Dancer Arm Loop Height Adjustment

Three different loop sensing arm operating positions are selected manually during set-up. By selecting the higher number, the zero point of the dancer arm is raised from its rest position to the angle shown (as indicated 0-2). The dancer arm will move from rest position to the angle selected before the straightener rolls begin to rotate.



Dancer Arm Loop Range Function



30 degree—Loop sensing arm travels through a full 30 degree arc to vary rotation speed from slow to full speed as controlled by % speed pot.



20 degree—Loop sensing arm travel through a 20 degree arc to vary speed from slow to full speed as controlled by % speed pot.



10 degree— Loop sensing arm travels through a 10 degree arc to vary rotation speed from slow to full speed as controlled by % speed pot.

STANDARD STRAIGHTENER COMPONENTS

Curve Up/Down Adjustment

Some applications have dies that cannot accept anything but flat stock and other dies run better with the material curving up or down to miss the built in edge required in the die. Before this feature was added, operators would under straighten or over straighten the material to suit their needs but in doing so would severely change the material entering the die. This not only caused feeding problems but part quality problems. With this feature, curve up or down can be accomplished by changing the position of the rolls without stressing the material.

Entrance Guide Roll Block

All straighteners are shipped with an entrance guide roll block. This block contains a roller and two quick release adjustable edge guides.

OPTIONAL STRAIGHTENER COMPONENTS

Entrance Cascade Roll

The entrance cascade roll assembly is used to maintain a support arc for stock entering a feed. The cascade roll has three extra rollers to help the material flow better. It is a direct replacement to the guide roll block and has the same bolt pattern.

Exit Cascade Roll

The straightener is shipped with the exit side pre-drilled for the cascade roll or guide roll block. The entrance and exit use the same components.

Dial Indicator Gauges

The SC straighteners are built with the machining complete to add on the dial indicator gauges. The need of this feature becomes apparent when many different materials with varying thickness are used. After setting up a material for straightening, record the gauge positions and then the next time the material is used, use the recorded information for a faster setup.

Angle Bracket

Rapid Air offers this accessory that mounts between the straightener head and the base. It angles the exit side of the straightener twelve degrees lower than the entrance side. This feature works very well when using the straightener to pull off a non-powered reel.

OPERATION

Once the straightener has been tested and all the functions work then it should be tested for what it was designed to do and that is to remove coil set.

Retract all of the idler rolls and the exit pinch roll to a position so when the cover is closed the material is not being deformed. Open the cover of the straightener and position the edge guides for maximum width. Cut and place about a four foot length of the material onto the straightener rolls with the exit end of the material extending through the exit pinch rolls and centered from side to side in the straightener. Close the cover and latch it. Adjust the exit pinch roll enough to grip and hold the material. Adjust the edge guides so that they just touch the material.

Adjust the first idler roll, this is the one nearest the entrance of the straightener, so that it deforms the material no more than the thickness of the material. **(NOTE: one full turn on the roll adjustment screw is**

equal to about .050 roller movement)

Adjust the remaining four in succession, each with a decreasing degree of stock deformation until the fifth idler roll just touches the material. Run the material to check that the exit pinch roll is not slipping on the material, readjust if necessary. This piece will still have coil set in the first two feet of the material as it was not run through the complete straightening cycle. At this time, this piece could be rerun and checked for straightness or a new piece could be cut and run and then be checked.

A good check is to guide the exiting material, keeping it parallel to the rolls, until the run is complete and then hold one end of the material in the air while peering down the length of the material. If the material still has "coil set" then readjust roll pressure on the last roll, towards the exit end but before the pinch roll, until the material is straight. Run one or more short length setups while making final adjustments. Once the proper setting has been determined, the

quick release top maintains the adjustment during loading.

Thread the material from the reel through the straightener, under the dancer arm, and into the pulling device leaving ample loop between the straightener and the pulling device. If the material thickness is such that when exiting the straightener, it will not let the dancer arm down to the rest position, then either lengthen the dancer arm or adjust the loop height until the straightener stops feeding.

Set the % speed potentiometer to 50% for a starting position and start the pulling device to have the material feeding. If the straightener gets finished and stops before material is needed again then the straightener is set to feed too fast, slow it down by adjusting the % speed potentiometer. The ideal straightening is to have the straightener slightly exceed the feed rate required. This minimizes the starting and stopping and resultant stock deformation.

MAINTENANCE

Lubrication

Worm gear reducer

The reservoir oil capacity is about 4 oz. The reservoir oil should be changed every 2000 hours and should be filled the oil level site gauge. Use MOBILE 600W cylinder oil or equivalent. This is a non-synthetic oil.

Gear transmission

The reservoir oil capacity is about 4 oz. The reservoir oil should be changed every 2000 hours and should be filled the oil level site gauge. Use MOBILE 600W cylinder oil or equivalent. This is a non-synthetic oil.

Rolls

Although the rolls should be cleaned periodically they never have to be greased as all the rolls have permanently lubricated bearings.

TROUBLESHOOTING GUIDE

MAIN SWITCH ON BUT NOT LIT

1. CB tripped.
 - a. Reset CB.
2. Unit not plugged into main power.
 - a. Plug into main power source.
3. No power in incoming line.
 - a. Check outlet.
 - b. Check power cord.
4. Loose wiring.
 - a. Check terminals and connections.

MOTOR CREEPS IN STOP POSITION

1. R1 & R3 pot on 69100034 board not correctly adjusted.
 - a. Readjust pots so rollers stop. Call factory.

UNIT TURNS BUT WON'T JOG

1. Selector switch not in jog position.
 - a. Select jog.
2. Jog pot on 69100076 board not adjusted correctly.
 - a. Adjust pot. Call factory.
3. Maximum speed pot on RAMM board set too low.
 - a. Adjust pot.

UNIT ON BUT MOTOR WON'T RUN. (ARMATURE VOLTAGE PRESENT – ON RAMM BOARD)

1. Check motor wiring and fuse.
 - a. Replace motor cord and correct motor wiring. Call factory.
2. Check motor.
 - a. Worn brushes or motor defective. Call factory.

UNIT ON BUT MOTOR WON'T RUN. (NO ARMATURE VOLTAGE ON RAMM BOARD)

1. Selector switch not in run position.

- a. Turn selector switch to run position.
2. If running with a dancer arm control.
 - a. Check that the external/loop switch is in the loop arm position.
3. If running with external control.
 - a. Check that the external/loop arm switch is in the external position.
4. Height switch setting too high.
 - a. Set height setting to "0".
5. Percent speed pot set too low.
 - a. Adjust percent speed pot to 100%.
6. Fuses blown.
 - a. Check fuses and circuit breaker.
7. No AC voltage at DC drive board.
 - a. Check wiring.
8. Check signal voltage between P2 to I2 on DC drive.
0-6 VDC—RAMM
0-9 VDC—Regen Drive
while moving dancer arm.
 - a. If there is a signal, check continuity between I1 & I2.
 - b. If no continuity, replace D.C. drive or call factory.
9. Check line voltage input of 69100034 board, 120 VAC, TB-1.
 - a. Check wiring. Call factory.
10. Check pico fuse 69100034 board (f1).
 - a. Replace fuse, 1 amp pico fuse — call factory.
11. Check for 0-12 VDC between pin #1 (=V) and pin #2 (GND) of panduit connector TC3 on board #69100034.
 - a. If no voltage present call factory.

12. Check for DC voltage between pin #6 (VO) and pin #2 (GND) of panduit connector TC3, on board 69100034, while moving the dancer arm from minimum to maximum position.
 - a. If voltage is present, turn power off and check the ribbon cable connections between panduit connector #TC3 of 69100034 board and panduit connector #TB-4 of 69100076 board. This should be a continuity check for tight connections. Call factory for assistance.
 - b. If voltage is not present move on to step 13.
13. Check voltage between pin #5 of TB-6 & pin #3 of TB-5 on 69100076 board while moving the dancer arm from minimum to maximum position.
 - a. If voltage varies 2.5-4 volt from minimum to maximum position, the dancer arm pot is OK, but the 69100076 board could be defective. Call factory.
 - b. If voltage does not vary when moving the dancer arm from minimum to maximum position — call the factory for assistance.

69100034 TAUT STOCK OUTPUT

The 69100034—Proportional control board has a taut stock output. The output must be wired to a solid state relay as the max current draw is 20 MA. The solid state relay's contact can then be incorporated into the electrical control circuitry.

The output can be wired so that the relay is either on or off with the dancer arm down. When the dancer arm reaches the set point for taut stock, the relay switches state.

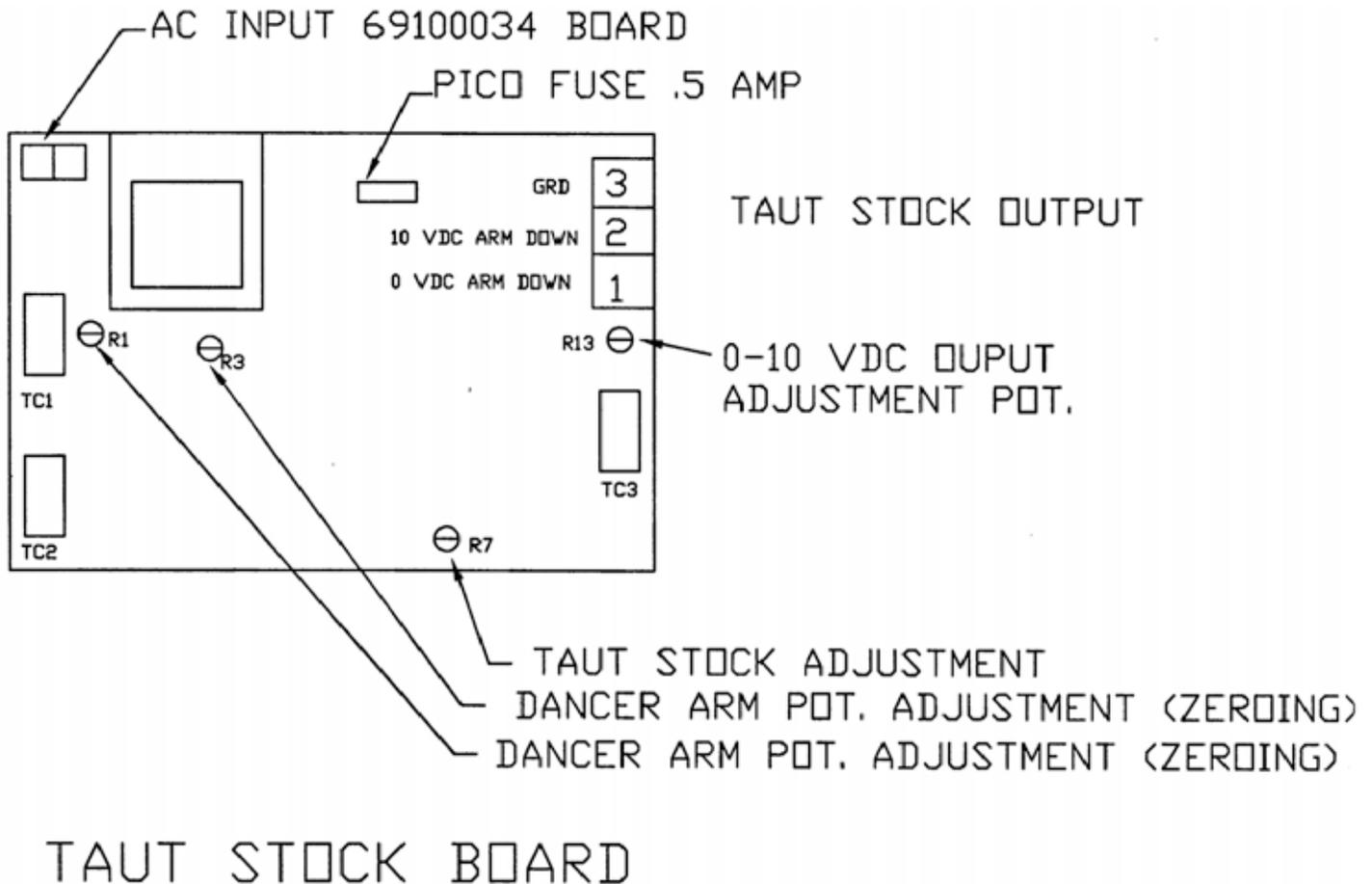
The taut stock height set point is set by raising the dancer arm to a position that the material is taut and then adjusting pot R7 so the output changes state. Lower and raise the dancer arm a few times to check that the set point repeats and then the set point repeats and then the task is finished.

The potentiometer that is located just below the taut stock terminal strip is used for presetting the max voltage output requirement for a particular

drive. A RAMM DC drive needs 6 VDC for max motor speed so turn the pot fully counter-clockwise. A minarik drive board needs 10 VDC for max motor speed so turn the pot fully clockwise.

The following is a brief wiring diagram for the taut stock.

3	GRD
2	10 VDC out with dancer arm down
1	0 VDC out with dancer arm down



SAFETY WARNING – PLEASE READ CAREFULLY

RAMM Solid State DC Motor Speed Control

This product should be installed and serviced by a qualified technician, electrician or electrical maintenance personnel familiar with its operation and the hazards involved. Proper installation (see instruction information which accompanies product), which includes wiring, mounting in proper enclosure, fusing or other over current protection and grounding, can reduce the chance of electrical shocks, fires or explosion in this product or products used with this product, such as electric motors, switches, coils solenoids and/or relays. Eye protection must be worn when working with control under power. This product is constructed of materials (plastics, metals, carbon, silicon, etc.) which may be a potential hazard. Individual material safety data sheets (MSDS) are available upon request. Proper shielding, grounding and filtering of

this product can reduce the emission of radio frequency interference (RFI) which may adversely affect sensitive electronic equipment. If information is required on this product, contact our factory. It is the responsibility of the ultimate user of this product to read and comply with this safety warning. (SW effective 1/89)

*****IMPORTANT*****
YOU MUST READ THESE INSTRUCTIONS BEFORE OPERATING CONTROL

1. Be sure AC line voltage corresponds to control voltage.

2. Install the correct Plug-In Horsepower Resistor according to armature voltage and motor horsepower.
3. Recheck connections: AC line to L1 and L2; armature to A+ and A- and field (Shunt motors only to F+ and F-.) (**Note:** If motor runs in improper direction, interchange armature leads.)
4. Install proper AC line fuse and armature fuse as required.
5. Nominal trimpot settings are as follows (expressed in % of full CW rotation):

TABLE 1: NOMINAL TRIMPOT SETTINGS

MIN (minimum speed):	15%	CL (current limit/torque):	65%
MAX (maximum speed):	65%	ACCEL (acceleration start):	20%
IR (IR compensation):	25%	DECEL (deceleration stop):	20%

Plug-In Horsepower Resistor

A Plug-In Horsepower Resistor must be installed to match the RAMM to the motor horsepower and voltage. See table 2 for the correct value. Plug-In Horsepower Resistors are stocked by your distributor.

TABLE 2: PLUG-IN HORSEPOWER RESISTOR CHART*

MOTOR HORSEPOWER RANGE **		Plug-in Horsepower Resistor Resistance Value (ohms)	Rapid-Air Part Number
Armature Voltage 90-130 VDC	Armature Voltage 180 VDC		
1/4	1/2	.05	69100529
1/2	1	.025	69100530
3/4	1-1/2	.015	69100534
1***	2***	.01	69100531

* Motor horsepower and armature voltage must be specified when ordering so that proper resistor will be supplied.

** For overlapping motor horsepower range use lower value Plug-In Horsepower Resistor.

*** Auxiliary heat sink must be used to achieve HP rating.

INTRODUCTION

RAMM Full Wave Solid State DC Motor Speed Control

The RAMM Full Wave Solid State DC Motor Speed Control represents the latest state-of-the-art design achievable through modern technology.

FEATURES INCLUDE:

Integrated Circuitry

Used to control and amplify command and reference levels with both closed and open loop feedback to provide superior motor regulation. (Speed changes due to load, line voltage, or temperature variations are held to minimum levels).

High Quality Components

Selected and tested for proven dependability.

Transient Protection

Used to prevent failure of the power bridge circuit caused by voltage spikes on the AC line.

High Reliability

When used in accordance with instructions in this manual, the RAMM will provide years of trouble-free operation.

A. INITIAL SETUP AND WIRING

General Instructions

1. Install proper size Plug-In Horsepower Resistor. (see table 2)
2. The RAMM can be connected to a standard 120V or 240V 50/60 Hz AC line (be sure the AC input voltage corresponds to the control voltage rating and the motor rating). (e.g. 90-130 VDC motor on 120VAC and 180 VDC motor on 240 VAC)

3. Follow the recommended supply wire sizes as per table 3.
4. Follow the NEC and other electrical codes that apply.

CAUTION: SEPARATE BRANCH PROTECTION MUST BE PROVIDED ON 240V CIRCUITS.

5. Connect control in accordance to connection diagram.

TABLE 3: MINIMUM SUPPLY WIRE SIZE REQUIREMENTS

Max. Motor Amps (DC Amps)	Max. Motor HP 90V	Max. Motor HP 180V	Max. Motor Run	Minimum Wire Size (AWG) Cu only Max. Motor Run
6.0	1/2	1	16	14
12.0	1	2	14	12*
16.0	1-1/2	3	12	12

* Maximum recommended wire size.

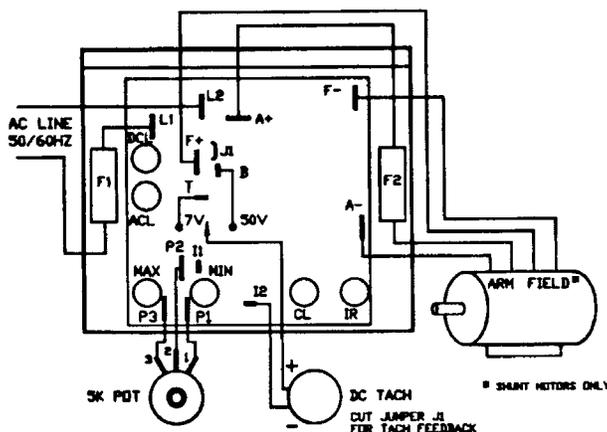


FIGURE 1: BASIC RAMM CONNECTION DIAGRAM

CAUTION: DO NOT BUNDLE POTENTIOMETER CONNECTIONS (P1, P2, P3) AND INHIBIT CONNECTIONS (I1, I2) WITH AC LINE OR MOTOR WIRES.

B. VOLTAGE FOLLOWING

All models can be controlled with an isolated analog reference voltage (0-6VDC) in lieu of the main speed potentiometer. The voltage is connected to P2 (+) and F-. The control output voltage will linearly follow the

input voltage. The source impedance of the input should be 10K ohms or less. The Min trimpot can be used to provide an offset speed. If an offset is not required adjust the Min to 0+ or 0- speed as desired. The Max trimpot is rendered inoperative in the voltage following mode. Use auxiliary trimpot to limit the control range. If the input signal is not isolated, or is a current signal (4-20 MA), the RAS1240D Signal Isolator must be used. It will allow direct connection to process controllers and microprocessors.

INTRODUCTION (CONT.)

CAUTION:

1. The voltage feeding P2 and F– must be isolated from the AC line. Do not ground P2 or F– to set up a zero ground reference.
2. Do not bundle signal wires to P2 and F– with AC line motor connections. If signal wires are over 18", use shielded cables.

C. FUSING

The RAMM has provision for a built in AC line fuse and armature fuse. The AC line fuse protects the control against catastrophic failure. If the fuse blows, the control is mis-wired, the motor is shorted or grounded, or the RAMM control is defective. The armature fuse provides overload protection for the motor and control. Choose the proper size armature fuse by multiplying the maximum DC motor amps by 1.7. On domestic 240 Volt AC lines, separate branch circuit protection for each line must be used. All fuses should be normal blow ceramic 3AG or ABC or equivalent.

1. AC Line Fuse is chosen according to the maximum rating of the control:
 - 12 AMP fuse for all motors up to 3/4 HP-90V and 1-1/2 HP-180VDC.
 - 25 AMP fuse for all motors 1 and 1-1/2 HP-90v and 2 and 3 HP-180VDC.
 (Use Buss ABC, Littlefuse 326 ceramic fuse or equivalent.)
2. Armature Fuse can be chosen in accordance with the fuse chart.

Note: The armature fuse is calculated based on the approximate full load DC current rating of the motor times a form factor of 1.5. If motor has characteristics not consistent with these approximations, a different fuse value may have to be used. Fuses are available from your distributor.

TABLE 4: ARMATURE FUSE CHART

Horsepower 90 VDC Motor	Horsepower 180 VDC Motor	Approx. DC Motor Current (Amps)	Fuse Rating (AC Amps)
1/4	1/2	2.5	4
1/2	1	5.0	8
3/4	1-1/2	7.5	12*
1	2	10.0	15
1-1/2	3	15.0	25*

* Also used as AC line fuse.

ADJUSTMENTS AND CONTROL FUNCTIONS

RAMM Adjustments And Control Functions

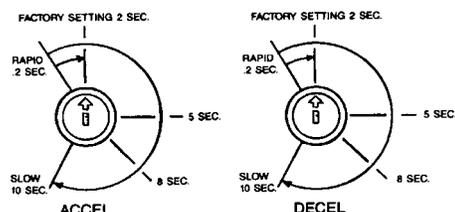
WARNING: If adjustments are made under power, insulated adjustment tools must be used and eye protection must be worn.

The RAMM has been factory adjusted to provide 0-full speed using the speed control knob. Minimum and Maximum speed trimpots are provided to change the speed from other than 0-full speed. The Acceleration (ACCEL) trimpot is provided to allow for a smooth start over an adjustable time period each time the AC power is applied or the speed pot is rotated. The DECEL trimpot controls the amount of ramp-down when the speed pot is adjusted to a lower speed. The Current Limit (CL, or torque output) adjustment is factory set to approximately 1-1/2 times the motor rating. The IR Compensation (IR) is factory adjusted to provide excellent motor regulation under normal operation.

NOTE: In order for the IR comp. and CL trimpot settings to be correct, the proper Plug-in Horsepower Resistor must be installed for the particular motor and input voltage being used. Do not attempt to change the settings of the trimptots unless absolutely necessary since they are factory adjusted to near optimum settings.

The following procedure, presented in order of adjustment sequence, should be used when readjusting all trimptot functions.

FIGURE 2: ACCEL/DECEL TRIMPOT ADJUSTMENT



A. Acceleration Start. The ACCEL is factory set at approximately .2 seconds. To readjust to different times, set the knob to the desired position as indicated in Fig 2.

B. Deceleration. The DECEL is factory set to provide a ramp-down time of .2 seconds. To change the ramp-down time, adjust the DECEL trimptot as indicated in Fig 2.

C. Minimum Speed Adjustment. If a higher than zero minimum speed is desired, readjust the minimum speed by turning the speed control knob to zero setting (full CCW position). Then adjust the Min. Speed Trimptot to the desired setting.

NOTE: The min. speed adjustment will affect the max. speed setting. Therefore, necessary to readjust the max. speed after the min. speed is adjusted.

D. Maximum Speed Adjustment. Turn Speed Control Knob to full speed (maximum CW position). Adjust max. speed trimptot to new desired setting.

NOTE: Do not attempt to adjust the max. speed above the rated motor RPM since unstable motor operation may occur. For moderate changes in the max. speed, there will be a slight effect on the min. speed setting.

E. Current Limit (CL/Torque Adjustment). CL circuitry is provided to protect the motor and control against overloads. The CL also limits the inrush current to safe level during startup. The CL is factory set to approximately 1.5 times the full load rating of the motor. (CL trimptot is nominally set to approximately 65% of full CW rotation).

To set the CL to factory specifications adjust as follows:

1. Set speed control knob at approximately 30-50% CW rotation. Set CL

- trimptot to full CCW position.
2. Connect a DC ammeter in series with the armature lead.
3. Lock shaft of motor (be sure CL pot is in full CCW position). Apply power and rotate CL pot CW slowly until DC ammeter reads 1.5 times motor rating (do not exceed 2 times motor rating, max. CW position.)

NOTE: If only an AC ammeter is available, it can be installed in series with the AC line. Follow above instructions; however, set AC amperage at .75 times motor rating.

F. IR Compensation Adjustment. IR compensation is provided to substantially improve load regulation. If the load presented to the motor does not vary substantially, the IR adjustment may be set at a minimum level (approximately 1/4 of full setting). The control is factory adjusted to approximately 3% regulation. If superior performance is desired (less than 1% speed change of base speed from 0 to full load), then the IR comp. should be adjusted as follows:

NOTES: 1. Excessive IR comp. will cause control to become unstable, which causes motor cogging. 2. For tach feedback applications the IR comp can be set to minimum rotation (full CCW).

1. Set IR comp. trimptot at approximately 25% of CW rotation. Run motor unloaded at approximately 1/3 speed and record RPM.
2. Run motor with maximum load and adjust IR comp. trimptot so that the motor speed under load equals the unloaded speed per step 1.
3. Remove load and recheck unloaded RPM. If unloaded RPM has shifted, repeat procedure for more exact regulation.

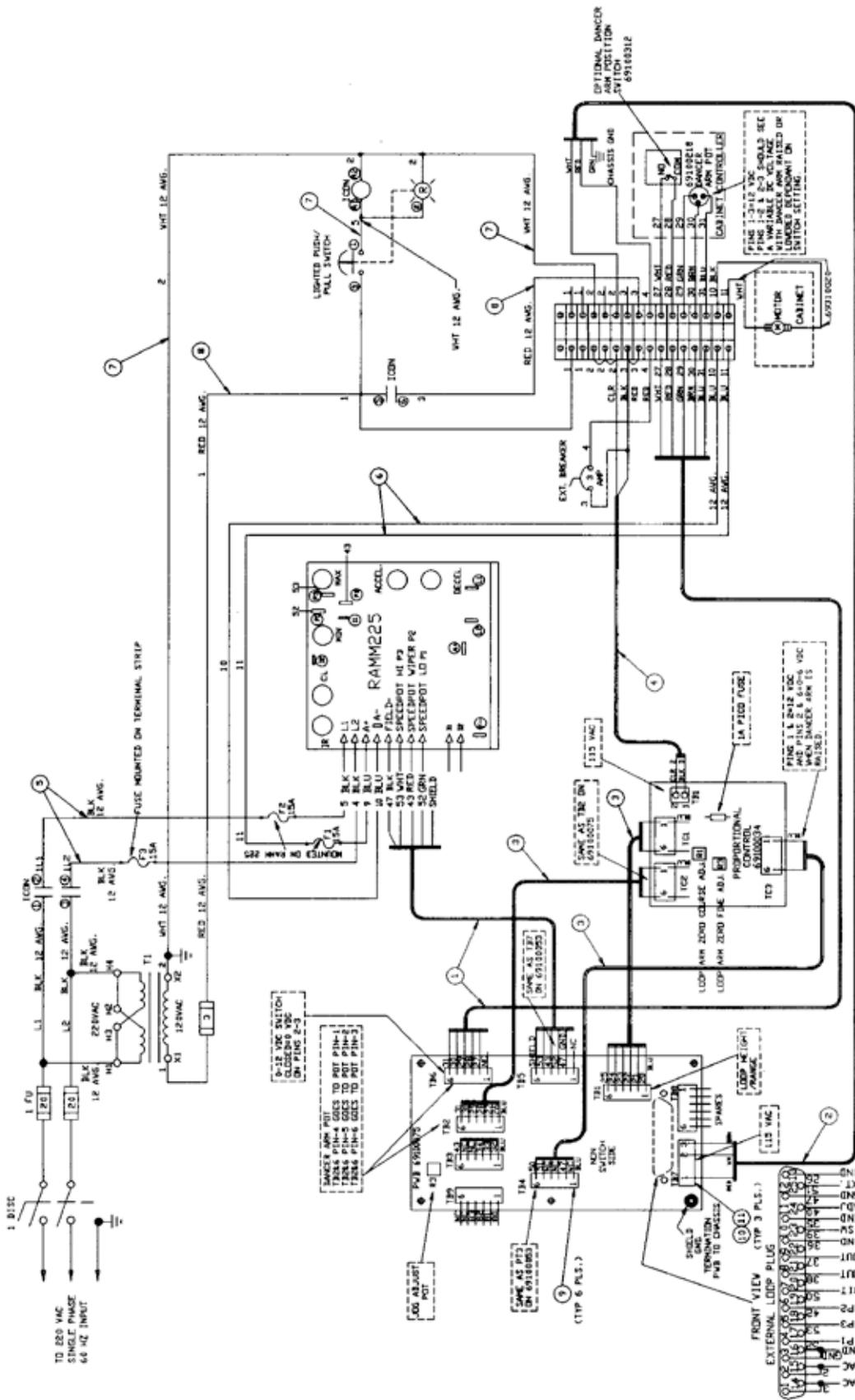
The RAMM is now compensated to provide minimal speed change under large variations of applied load.

WARRANTY

Limited Warranty – RAMM 125, 225, 225D

For a period of one (1) year from date of original purchase Rapid-Air Corporation will repair or replace without charge devices which our examination proves to be defective in material or workmanship. This warranty is valid if the unit has not been tampered with by unauthorized persons, misused, abused or improperly installed and has been used in accordance with the instructions and/or ratings supplied. The foregoing is in lieu of any other warranty or guarantee expressed or implied, and we are not responsible for any expense (including installation and removal), inconvenience, or consequential damage, including injury to any person, caused by items of our manufacture and/or sale. Some states do not allow certain exclusions or limitations found in this warranty so that they may not apply to you. In any event, Rapid-Air Corporation's total liability, under all circumstances, shall not exceed the full purchase price of this unit.

Wiring Diagram for High Speed Straighteners (3-HP)



855XX248

RAPID-AIR CORPORATION
 RICHMOND, VIRGINIA

WIRING DIAGRAM FOR HIGH SPEED STRAIGHTENERS (3-HP)

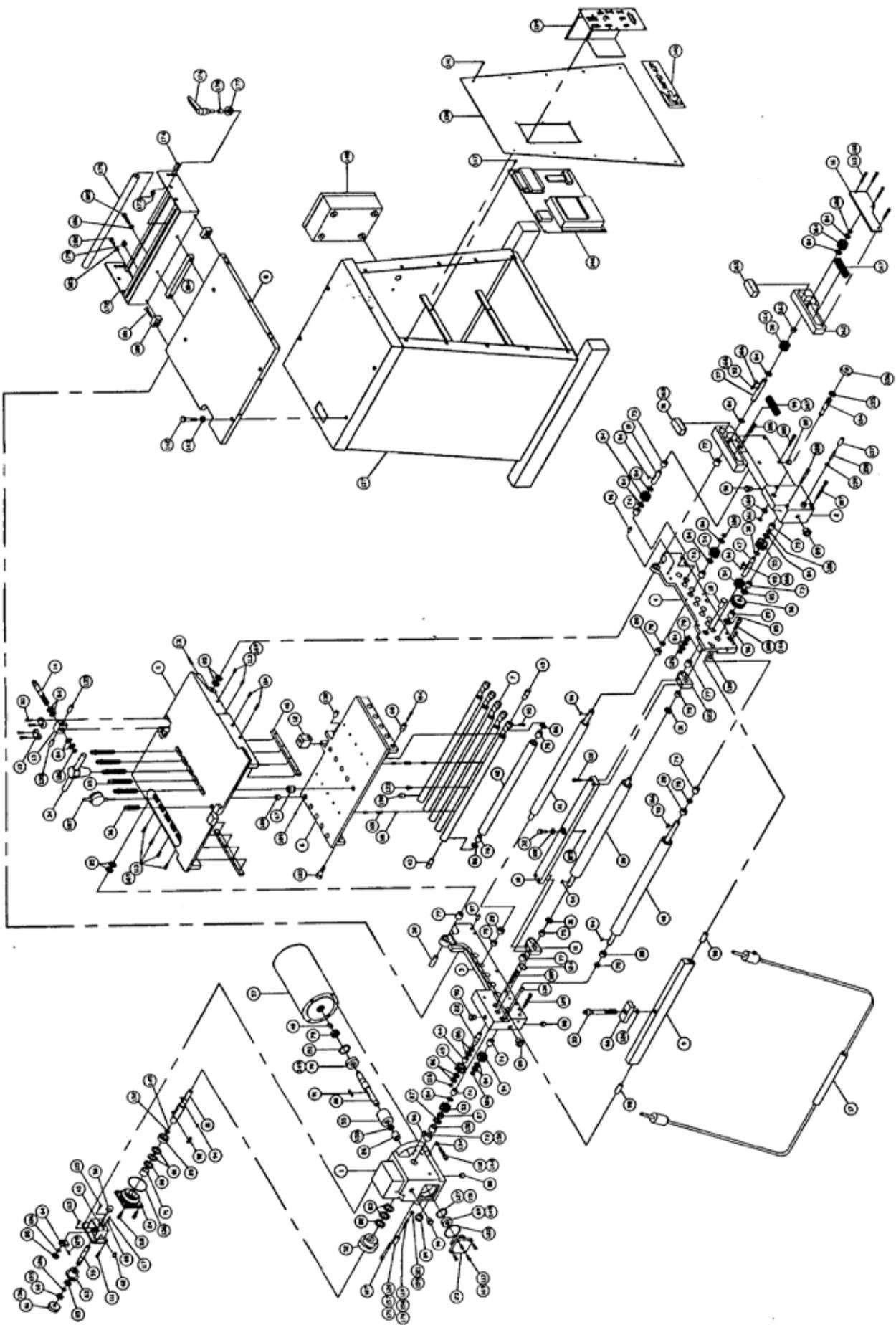
DATE: 11-11-57
 DRAWN BY: []
 CHECKED BY: []
 APPROVED BY: []

NO.	DESCRIPTION	QTY	UNIT
1	120VAC 1.70 FUSE	1	PCB
2	220VAC TRANSFORMER	1	PCB
3	12 AWG WIRE	100	FT
4	1.5A FUSE	1	PCB
5	115VAC PROPORTIONAL CONTROLLER	1	PCB
6	1A 710D FUSE	1	PCB
7	120VAC 1.5A FUSE	1	PCB
8	120VAC 1.5A FUSE	1	PCB
9	120VAC 1.5A FUSE	1	PCB
10	120VAC 1.5A FUSE	1	PCB
11	120VAC 1.5A FUSE	1	PCB

120VAC 1.5A FUSE FOR 1.5A FUSE. AC FUSE MUST BE 250 AMP.

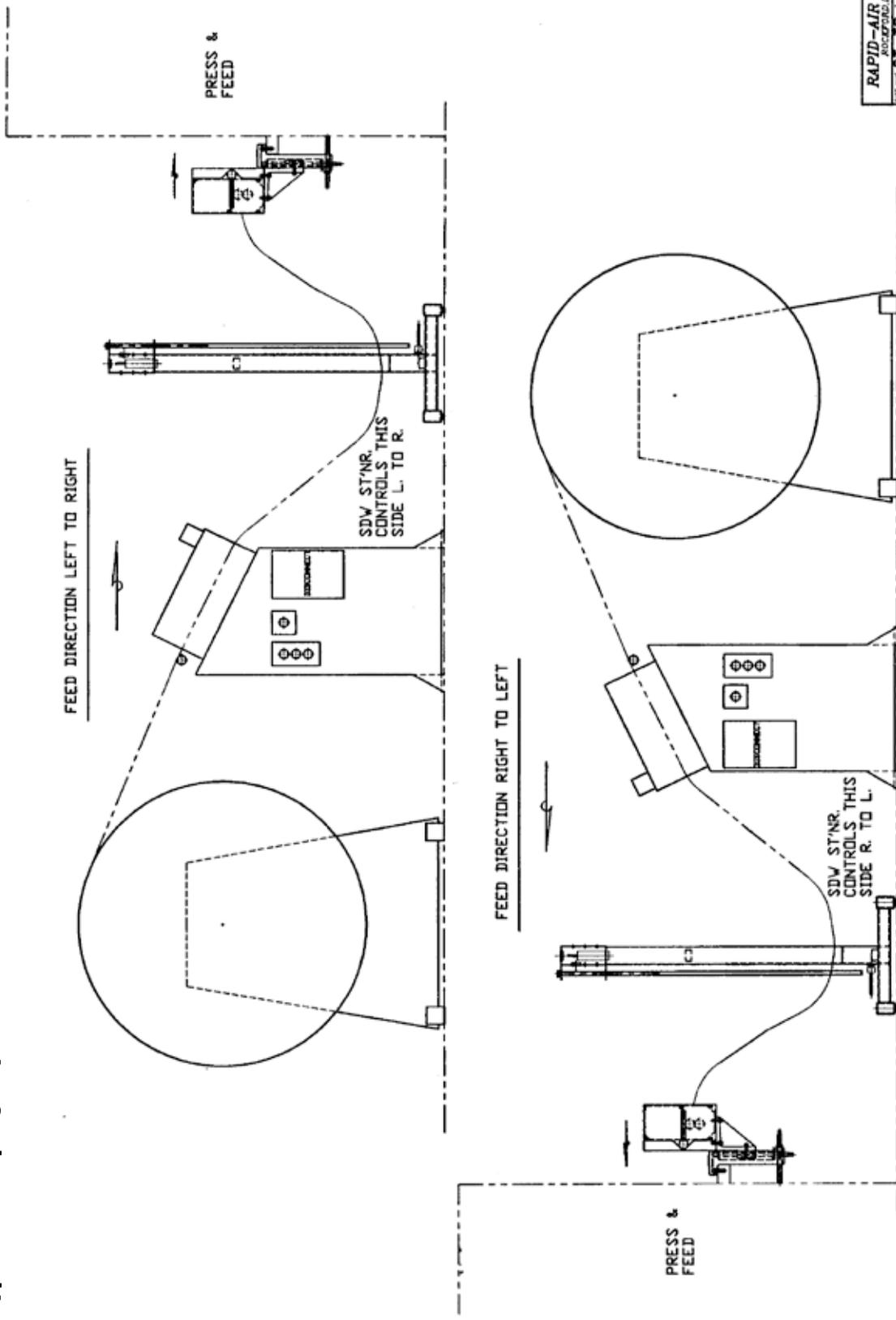
REF. WIRE AND CABLE COUNT

NO.	DESCRIPTION	QTY	UNIT
1	120VAC 1.5A FUSE	1	PCB
2	120VAC 1.5A FUSE	1	PCB
3	120VAC 1.5A FUSE	1	PCB
4	120VAC 1.5A FUSE	1	PCB
5	120VAC 1.5A FUSE	1	PCB
6	120VAC 1.5A FUSE	1	PCB
7	120VAC 1.5A FUSE	1	PCB
8	120VAC 1.5A FUSE	1	PCB
9	120VAC 1.5A FUSE	1	PCB
10	120VAC 1.5A FUSE	1	PCB
11	120VAC 1.5A FUSE	1	PCB



Parts List

Typical Stamping Layout



RAPID-AIR CORPORATION
 ADDY, ILL. 62424
 TEL. 618-438-1111

DATE: 6/1/74
 BY: G. W. S. S. / J. S. S.
 CHECKED: G. W. S. S. / J. S. S.
 DRAWING NO.: 174
 REV. NO.: D

NO.	REV.	DATE	BY	CHKD.